

A Decision Procedure for (Co)datatypes in SMT Solvers

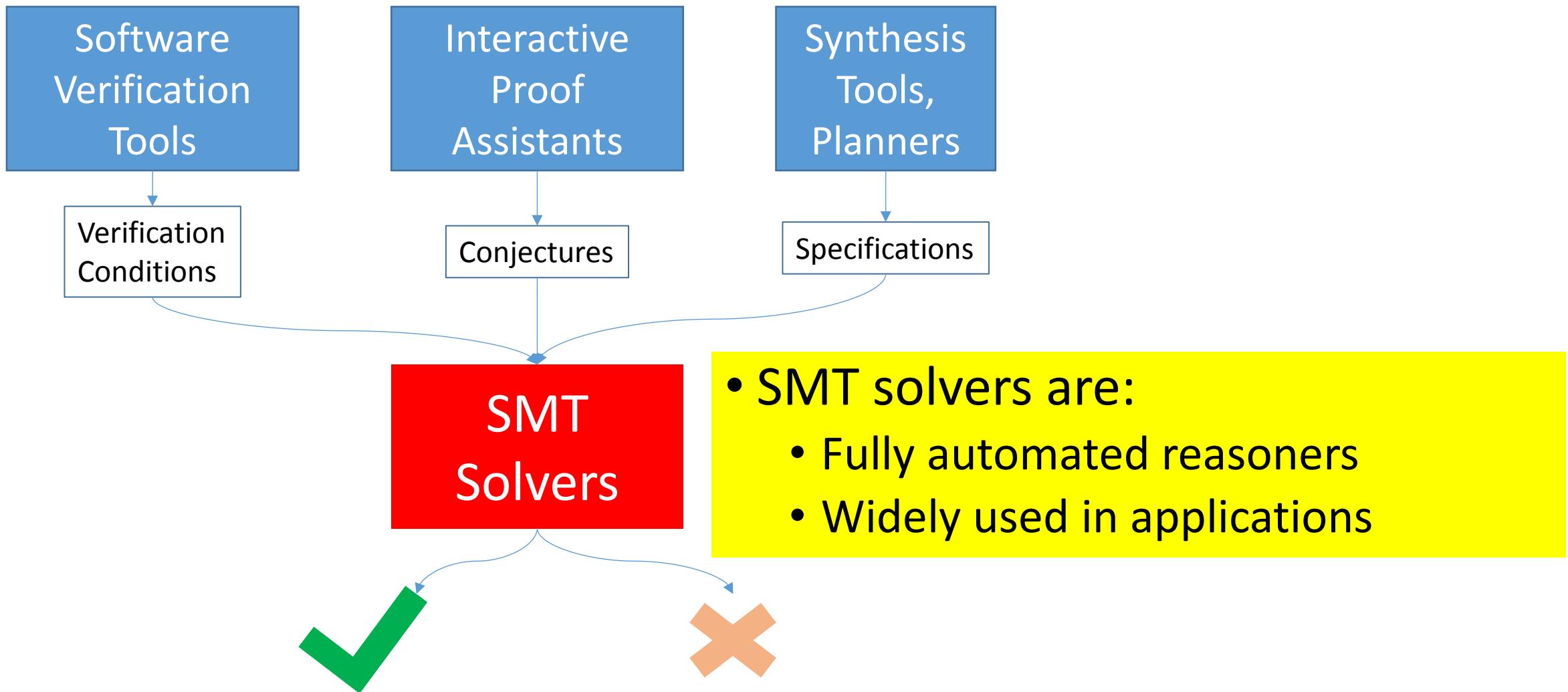
Andrew Reynolds

Jasmin Christian Blanchette

IJCAI sister conference track, July 12, 2016



Satisfiability Modulo Theories (SMT) Solvers



Common Theories Supported by SMT Solvers

- SMT solvers support:
 - Arbitrary Boolean combinations of ground *theory* constraints
 - Examples of supported theories:
 - Uninterpreted functions: $f(a) = g(b, c)$
 - Linear real/integer arithmetic: $a \geq b + 2 * c + 3$
 - Arrays: $\text{select}(A, i) = \text{select}(\text{store}(A, i+1, 3), i)$
 - BitVectors: $\text{bvule}(x, \#xFF)$
 - Algebraic Datatypes: $x, y : \text{List}; \text{tail}(x) = \text{cons}(0, y)$
 - ...

Common Theories Supported by SMT Solvers

- SMT solvers support:
 - Arbitrary Boolean combinations of ground *theory* constraints
 - Examples of supported theories:
 - Uninterpreted functions: $f(a) = g(b, c)$
 - Linear real/integer arithmetic: $a \geq b + 2 * c + 3$
 - Arrays: $\text{select}(A, i) = \text{select}(\text{store}(A, i+1, 3), i)$
 - BitVectors: $\text{bvule}(x, \#xFF)$
 - Algebraic Datatypes: $x, y : \text{List}; \text{tail}(x) = \text{cons}(0, y)$

...Recurrent Questions:

- What theories are **useful in applications?**
- What theories can we **handle efficiently?**

Common Theories Supported by SMT Solvers

- SMT solvers support:
 - Arbitrary Boolean combinations of ground *theory* constraints
 - Examples of supported theories:
 - Uninterpreted functions: $f(a) = g(b, c)$
 - Linear real/integer arithmetic: $a \geq b + 2 * c + 3$
 - Arrays: $\text{select}(A, i) = \text{select}(\text{store}(A, i+1, 3), i)$
 - BitVectors: $\text{bvule}(x, \#xFF)$
 - **(Co)Algebraic Datatypes:** $x, y : \text{List} \mid \text{Stream}; \quad \text{tail}(x) = \text{cons}(0, y)$
 - Are of **importance** to the interactive proof assistant **Isabelle**
 - Can be decided by an **efficient decision procedure**

Introductory Examples



Introductory Examples

```
datatype nat =
```

```
    Z
```

```
    | S(nat)
```

```
datatype listτ =
```

```
    Nilτ
```

```
    | Consτ( τ, listτ)
```

Introductory Examples

```
datatype nat =
```

```
    z
```

```
  | S(nat)
```

```
datatype listτ =
```

```
    Nilτ
```

```
  | Consτ( τ, listτ)
```

```
codatatype enat =
```

```
    EZ
```

```
  | ES(enat)
```

```
codatatype llistτ =
```

```
    LNilτ
```

```
  | LConsτ( τ, llistτ)
```

Introductory Examples

datatype nat =

z

| S(nat)

datatype list_τ =

Nil_τ

| Cons_τ(τ, list_τ)

codatatype enat =

EZ

| ES(enat)

codatatype llist_τ =

LNil_τ

| LCons_τ(τ, llist_τ)

codatatype stream_τ =

SCons_τ(τ, stream_τ)

Introductory Examples

```
datatype nat =
```

```
    Z
```

```
  | S(nat)
```

```
datatype listτ =
```

```
    Nilτ
```

```
  | Consτ( τ, listτ)
```

*Codatatypes need not
be well-founded*

```
codatatype enat =
```

```
    EZ
```

```
  | ES(enat)
```

```
codatatype llistτ =
```

```
    LNilτ
```

```
  | LConsτ( τ, llistτ)
```

```
codatatype streamτ =
```

```
    SConsτ( τ, streamτ)
```

Introductory Examples



Introductory Examples

$x \neq S(x)$



Introductory Examples

$x \neq S(x)$

$\exists x. x = ES(x)$

Introductory Examples

$x \neq S(x)$

$\exists x. x = ES(x)$

Cyclic values exist

Introductory Examples

$x \neq S(x)$

$\exists x. x = ES(x)$

$x = ES(x)$

$y = ES(y)$

Cyclic values exist

Introductory Examples

$x \neq S(x)$

$\exists x. x = ES(x)$

$x = ES(x) = ES(ES(ES(\dots)))$

$y = ES(y) = ES(ES(ES(\dots)))$

Cyclic values exist

Introductory Examples

$$x \neq S(x)$$

$$\exists x. x = ES(x)$$

$$\left. \begin{array}{l} x = ES(x) = ES(ES(ES(\dots))) \\ y = ES(y) = ES(ES(ES(\dots))) \end{array} \right\} =$$

Cyclic values exist

Introductory Examples

$$x \neq S(x)$$

*...but they are
equal up to
their expansion*

$$\exists x. x = ES(x)$$

Cyclic values exist

$$\left. \begin{array}{l} x = ES(x) = ES(ES(ES(\dots))) \\ y = ES(y) = ES(ES(ES(\dots))) \end{array} \right\} =$$

Introductory Examples

$$x \neq S(x)$$

*...but they are
equal up to
their expansion*

$$\exists x. x = ES(x)$$

Cyclic values exist

$$\left. \begin{array}{l} x = ES(x) = ES(ES(ES(\dots))) \\ y = ES(y) = ES(ES(ES(\dots))) \end{array} \right\} =$$

μ -notation:

$$xs = LCons(1, \mu ys. LCons(0, LCons(9, ys)))$$

denotes the infinite sequence 1,0,9,0,9,0,9,...

Introductory Examples



Introductory Examples

`xs = LCons(0, LCons(1, LCons(2,...)))`

Acyclic infinite values exist

Introductory Examples

*datatype values =
all finite ground
constructor terms
(and only those)*

`xs = LCons(0, LCons(1, LCons(2,...)))`

Acyclic infinite values exist

Introductory Examples

datatype values =
all finite ground
constructor terms
(and only those)

`xs = LCons(0, LCons(1, LCons(2,...)))`

Acyclic infinite values exist

codatatype values =
all finite **or infinite**
ground constructor terms
(and only those)

A Degenerate Case

- Recursive datatypes are infinite
- Corecursive codatatypes admit infinite values
- Ergo: corecursive codatatypes are infinite?

A Degenerate Case

- Recursive datatypes are infinite
- Corecursive codatatypes admit infinite values
- Ergo: corecursive codatatypes are infinite?

Counterexample:

codatatype stream_{unit} = SCons(unit, stream_{unit})

datatype unit = Unity

⇒ “Corecursive singletons”

Our contributions

- Generalized [Barrett et al. 2007] (used in CVC3) to codatatypes
 - First decision procedure for codatatypes in SMT solvers
- Efficient implementation in CVC4
- Evaluation on Isabelle benchmarks

Calculus for Theory of (Co)datatypes \mathcal{DC}

- **Inputs:**
 - A finite set of literals E
- **Outputs:**
 - Either “ E is unsatisfiable” or “ E is satisfiable”
- Can be described as a set of derivation rules which
 - Add additional literals to E until saturated or conflict

Calculus: Guarded Assignment Form

- Derivation rules of calculus written in **guarded assignment form**:

$$\frac{\text{... premises on } E\text{...}}{E := E'} \text{ [rule]}$$

- For example:

$$\frac{t=s, s=r \in E}{E := E, t=s} \text{ trans}$$

- Derivation rules may have \perp as conclusion:

$$\frac{t=s, t \neq s \in E}{\perp} \text{ conflict}$$

Calculus: Derivation Tree

$$\begin{array}{c} t=s, s=r, t \neq r \\ \hline t=s, s=r, t \neq r, t=r \\ \hline \perp \end{array}$$

trans
conflict

- A node is a set of literals
- Each node obtained as result of successfully applying rule to parent
- The derivation terminates when:
 - All leaves are \perp ... input is **unsatisfiable**
 - Some node is saturated ... input is **satisfiable**

Part 1: Bidirectional Closure

$$\frac{t \in \mathcal{T}(E)}{E := E, t \approx t} \text{ Refl}$$

$$\frac{t \approx u \in E}{E := E, u \approx t} \text{ Sym}$$

$$\frac{s \approx t, t \approx u \in E}{E := E, s \approx u} \text{ Trans}$$

$$\frac{\bar{t} \approx \bar{u} \in E \quad \mathbf{f}(\bar{t}), \mathbf{f}(\bar{u}) \in \mathcal{T}(E)}{E := E, \mathbf{f}(\bar{t}) \approx \mathbf{f}(\bar{u})} \text{ Cong} \qquad \frac{t \approx u, t \not\approx u \in E}{\perp} \text{ Conflict}$$

$$\frac{\mathbf{C}(\bar{t}) \approx \mathbf{C}(\bar{u}) \in E}{E := E, \bar{t} \approx \bar{u}} \text{ Inject}$$

$$\frac{\mathbf{C}(\bar{t}) \approx \mathbf{D}(\bar{u}) \in E \quad \mathbf{C} \neq \mathbf{D}}{\perp} \text{ Clash}$$

- \mathbb{E} contains its upwards (congruence) and downwards (unification) closure

Part 2: Acyclicity and Uniqueness

- To determine datatype values are **acyclic**, codatatype values are **unique**:
 - Compute the class of values $\mathcal{A} [t]$ for each (co)datatype term t
 - For example:
 - $\mathcal{A} [t] := \mu x . C (x)$: the value of t is $C (C (C (\dots)))$
 - $\mathcal{A} [t] := \mu x . C (y)$: the top symbol of t is C

Part 2: Acyclicity and Uniqueness

$$\frac{\delta \in \mathcal{Y}_{dt} \quad \mathcal{A}[t^\delta] = \mu x. u \quad x \in \text{FV}(u)}{\perp} \text{ Acyclic}$$

$$\frac{\delta \in \mathcal{Y}_{codt} \quad \mathcal{A}[t^\delta] =_\alpha \mathcal{A}[u^\delta]}{E := E, t \approx u} \text{ Unique}$$

- Rule **Acyclic**:

- Checks whether $\mathcal{A}[t]$ contains a bound variable for some datatype term t
- For example: $E = \{ x = S(x) \}$
 - $\mathcal{A}[x] = \mu \tilde{x}. S(\tilde{x})$, thus $E \not\models_{DC} \perp$

- Rule **Unique**:

- Checks whether $\mathcal{A}[t], \mathcal{A}[u]$ are α -equivalent for some codatatype terms t, u
- For example: $E = \{ x = C(x), y = C(y) \}$
 - $\mathcal{A}[x] = \mu \tilde{x}. C(\tilde{x}) =_\alpha \mu \tilde{y}. C(\tilde{y}) = \mathcal{A}[y]$, thus $E \models_{DC} x = y$

Part 3: Splitting

$$\frac{\begin{array}{c} t^\delta \in \mathcal{T}(E) \quad \mathcal{F}_{\text{ctr}}^\delta = \{C_1, \dots, C_m\} \\ (\mathbf{s}(t) \in \mathcal{T}(E) \text{ and } \mathbf{s} \in \mathcal{F}_{\text{sel}}^\delta) \text{ or } (\delta \in \mathcal{Y}_{\text{dt}} \text{ and } \delta \text{ is finite}) \end{array}}{E := E, t \approx C_1(\mathbf{s}_1^1(t), \dots, \mathbf{s}_1^{n_1}(t)) \quad \dots \quad E := E, t \approx C_m(\mathbf{s}_m^1(t), \dots, \mathbf{s}_m^{n_m}(t))} \text{ Split}$$
$$\frac{t^\delta, u^\delta \in \mathcal{T}(E) \quad \delta \in \mathcal{Y}_{\text{codt}} \quad \delta \text{ is a singleton}}{E := E, t \approx u} \text{ Single}$$

- **Split** on the type of constructor for terms t
- Add equalities between all pairs of corecursive **singleton** terms t, u

Calculus is a Decision Procedure for \mathcal{DC}

- Calculus is:
 - **Terminating**
 - All derivation trees are finite
 - **Refutation-sound**
 - If a closed derivation tree exists, then indeed \mathbb{E} is unsatisfiable
 - **Model-sound**
 - If a saturated node exists, then indeed \mathbb{E} is satisfiable
 - Proof is constructive
- Thus, is a decision procedure

Implementation in SMT Solver

- Calculus is implemented as a DPLL(T) **theory solver** in CVC4



Implementation in SMT Solver

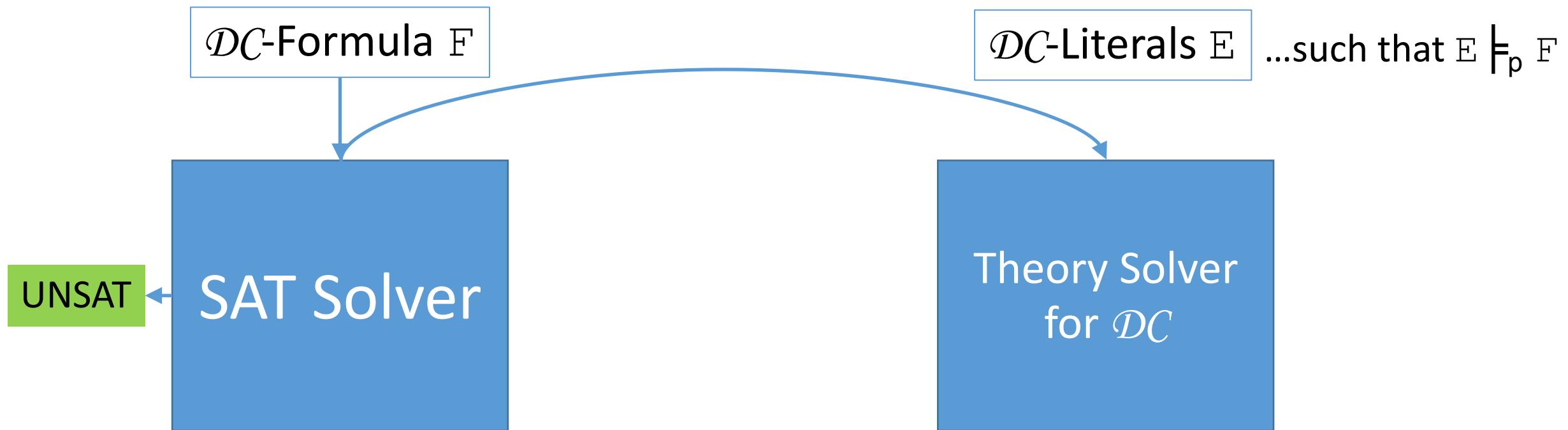
- Calculus is implemented as a DPLL(T) **theory solver** in CVC4



- SAT solver reasons about \mathcal{DC} -formulas at propositional level

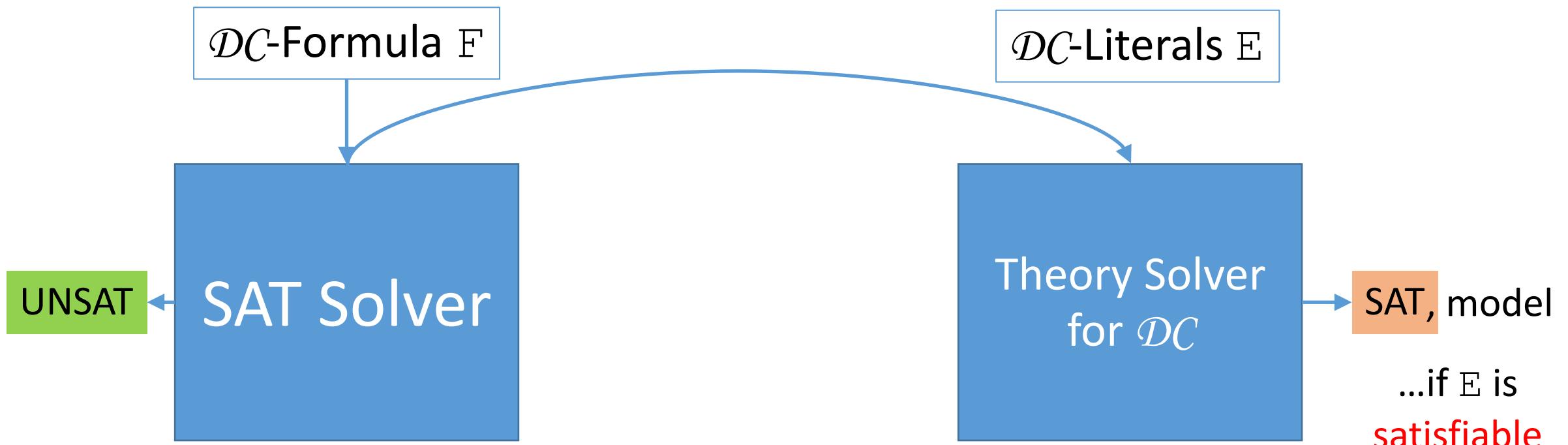
Implementation in SMT Solver

- Calculus is implemented as a DPLL(T) theory solver in CVC4



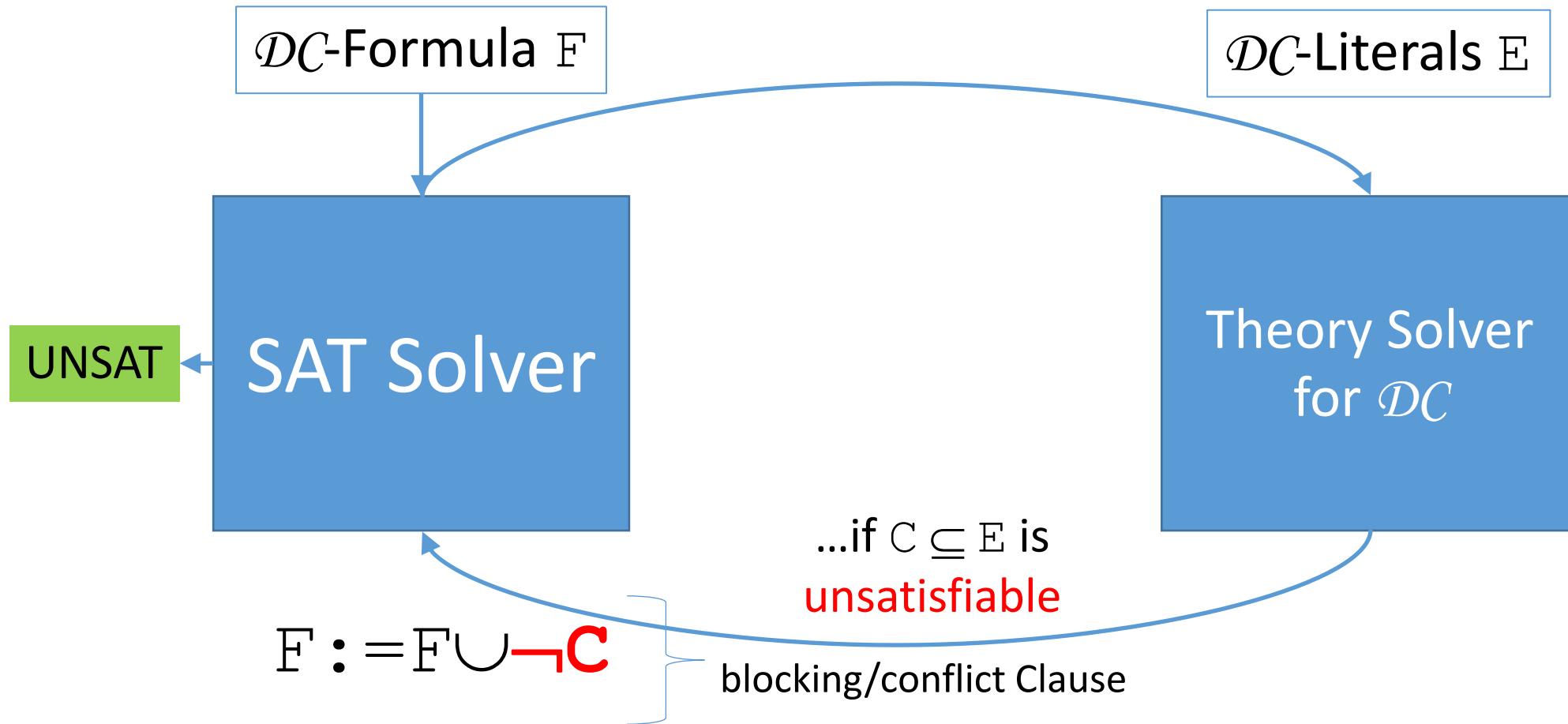
Implementation in SMT Solver

- Calculus is implemented as a DPLL(T) theory solver in CVC4



Implementation in SMT Solver

- Calculus is implemented as a DPLL(T) theory solver in CVC4



Evaluation

- Evaluated SMT solvers
 - **CVC4** : support for (co)datatypes from this talk
 - **Z3** : supports datatypes only
 - ...on Isabelle benchmarks from three libraries:
 - Isabelle Distribution (**Distro**)
 - Archive of Formal Proofs (**AFP**)
 - Two unpublished theories involving Bird and Stern-Brocot trees (**G&L**)
- ⇒Benchmarks involve quantified formulas + **(co)datatypes**

Evaluation

- Encodings:
 - With native (co)datatypes symbols e.g. tail, cons, nil:

$$\exists ab. \text{tail}(a) = \text{cons}(0, b)$$

- Without, axiomatization of uninterpreted symbols, e.g. f_{tail} , f_{cons} , f_{nil} :

$$\begin{aligned} & \forall xyzw. f_{\text{cons}}(x, y) \neq f_{\text{nil}} \\ & \forall xyzw. f_{\text{cons}}(x, y) = f_{\text{cons}}(z, w) \Rightarrow (x = z \wedge y = w) \\ & \forall x. x = f_{\text{cons}}(f_{\text{head}}(x), f_{\text{tail}}(x)) \vee x = f_{\text{nil}} \\ & \forall x. f_{\text{tail}}(f_{\text{cons}}(x, y)) = y \\ & \exists ab. f_{\text{tail}}(a) = f_{\text{cons}}(0, b) \end{aligned}$$

Evaluation : Results

		Distro		AFP		G&L		Overall	
		CVC4	Z3	CVC4	Z3	CVC4	Z3	CVC4	Z3
Weaker	No (co)datatypes	221	209	775	777	52	51	1048	1037
	Datatypes without Acyclic	227	–	780	–	52	–	1059	–
	Full datatypes	227	213	786	791	52	51	1065	1055
	Codatatypes without Unique	222	–	804	–	56	–	1082	–
	Full codatatypes	223	–	804	–	59	–	1086	–
	Full (co)datatypes	229	–	815	–	59	–	1103	–
Stronger									

- Stronger decision procedures subsume weaker ones
 - Rules for acyclicity, uniqueness contribute to precision of solvers
- Dedicated support for codatatypes in CVC4 **improves state of the art**
 - CVC4 with full (co)datatypes solves **1103**
 - CVC4 and Z3 with only datatypes solve 1065 and 1055 respectively

Summary

- Decision procedure for theory of (co)datatypes
 - Can be **implemented** in SMT solvers
- Evaluation on Isabelle benchmarks
 - **Beneficial to use stronger decision procedures**
- Future work:
 - Reconstruction of (co)datatype proofs in Isabelle
 - Apply to higher-order model finding
(Our original motivation)

Thanks!

- Paper:
 - 25th Conference on Automated Deduction (CADE-25)
- Implementation:
 - CVC4, available at <http://cvc4.cs.nyu.edu/downloads/>

